DDM-206A Online Conductivity Sensor User Manual



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User Notes

- Please read this manual carefully before use and save it for reference.
- Please follow the operating procedures and precautions in this manual.
- When receiving the instrument, please carefully open the package and check whether the instrument and accessories are damaged due to shipping. If any damage is found, please inform the manufacturer and distributor immediately, and keep the package for return.
- When the instrument fails, do not repair it yourself. Please contact the maintenance department of the manufacturer directly.

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\boldsymbol{I} 、 Application environment

- Drinking water / surface water / various water supply / industrial water treatment.
- Signal output: RS-485 (Modbus/RTU protocol).
- Convenient connection to third-party equipment such as PLC, DCS, industrial control computer, general controller, paperless recording instrument or touch screen.
- Immersion installation with 3/4 NPT pipe thread for easy submersible installation or installation in pipes and tanks.
- IP68 protection grade.

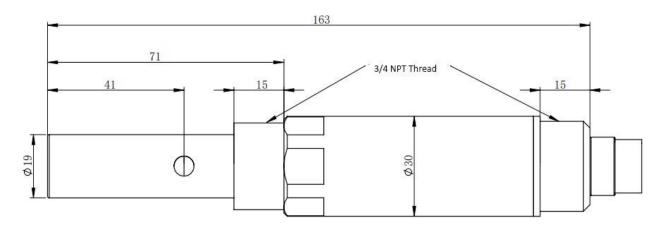
II 、 Technical performance and specifications

1. Technical parameters

Model	DDM-206A		
	0~20.00μS/cm 0.01		
Measuring range and	0~200.0μS/cm	0.1	
resolution	0~5000μS/cm	1	
	0~200.0mS/cm	0.1	
Precision	±1.5%F.S	., ±0.3°C	
Working temperature	0~60°C		
Working pressure	<0.6MPa		
Power supply	12~24VD	OC ±10%	
Signal output	RS-485(Modbus/RTU)		
Wetted material	ABS/SUS316L(Default) /PVC		
Mounting method	Immersion mounting, 3/4 NPT thread		
Cable length	5 meters, other lengths can be customized		
Temperature compensation	Auto temperature compensation (Pt1000)		
Calibration	Two-point calibration		
Power consumption	0.2W@12V		
Protection grade	IP68		

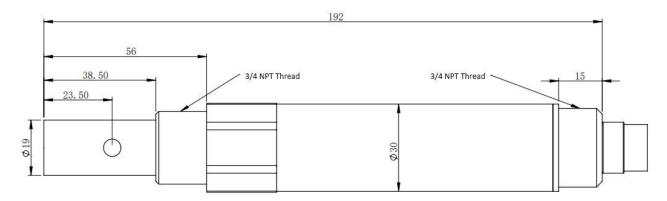
2. Dimensional drawing

2.1 DDM-206A-0.01



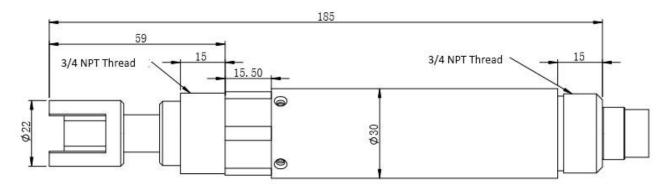
Note: The connector of the sensor is M16-5 core waterproof connector

2.2 DDM-206A-0.1



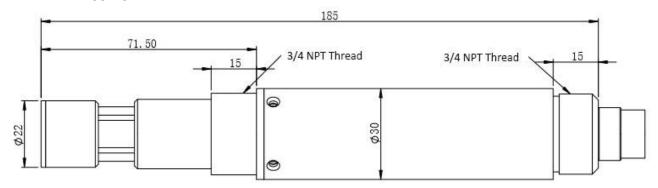
Note: the connector of the sensor is M16-5 core waterproof connector

2.3 DDM-206A-1.0



Note: the connector of the sensor is M16-5 core waterproof connector

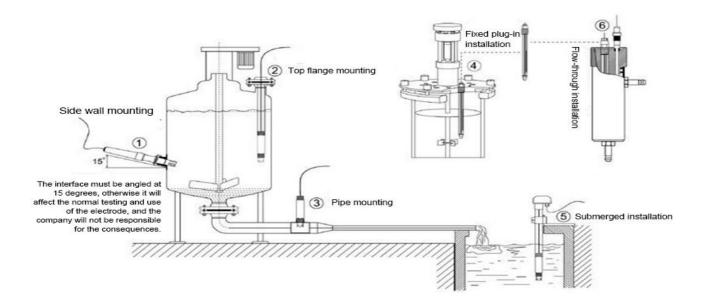
2.4 DDM-206A-SI



Note: the connector of the sensor is M16-5 core waterproof connector

III \ Installation and electrical connection

1. Installation



Note: The DDM-206A-1.0 and DDM-206A/206S-SI should be at least 2 cm from the bottom and side walls of the container during installing and testing.

2. Electrical connection

- a) Red line power cord (12 ~ 24V)
- b) Black line ground (GND)
- c) Blue line 485A
- d) white line 485B



After wiring is completed, it should be carefully checked to avoid incorrect connections before powering up.

Cable specification: Considering that the cable is immersed in water (including sea water) for a long time or exposed to the air, all the wiring points are required to do waterproof treatment, the user cable should has certain corrosion resistance.

IV. Maintenance

1. Use and maintenance

Conventional electrodes require periodic cleaning and calibration, and the maintenance cycle is determined by the customer based on his or her own operating conditions.

Cleaning method for conventional electrode: Remove the attached material with a soft brush (be careful to avoid scratching the surface of the electrode), then rinse with distilled water, and then perform calibration.

Electrode cleaning method:

- The inductive salinity electrode is basically maintenance-free, and its normal operation will not be affected by pollution or slight scaling of the shell.
- If it needs clean, use a soft brush or sandpaper to remove attachments, and then clean with distilled water, calibration after operation.
- Because the inductive electrode often works in the environment which is easy to scale or dirty, the cleaning strength can be increased appropriately. Slight scratches on the electrode surface will not affect the normal operation of the electrode, but it is necessary to avoid penetrating the electrode shell.

2. Calibration

a) Zero calibration

Rinse the sensor with distilled water and blot the liquid with filter paper. Place the sensor on the power supply and place it in the air for about 3 minutes. After the value is stable, perform zero calibration. The calibration instructions are detailed in the appendix.

b) Slope calibration

Place the electrode vertically in a standard solution (10% full scale - full scale). Note that the electrode is at least 2 cm from the bottom and side walls of the vessel for slope calibration. The calibration instructions are detailed in the appendix.

V 、 Quality and service

1. Quality assurance

 The quality inspection department has standardized inspection procedures, advanced and perfect testing equipment and means, and strictly in accordance with the regulations, to do

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72-hour aging test and stability test on the product, and not to allow one unqualified product to leave the factory.

- The receiving party directly returns the product batch with a failure rate of 2%, and all the costs incurred are borne by the supplier. The reference standard refers to the product description provided by the supplier.
- Guarantee the quantity of goods and the speed of shipment.

2. Accessories and spare parts

This product includes:

- 1 sensor
- 1 copy of the instruction manual
- 1 certificate
- Calibration solution (optional)

3. After-sales service commitment

The company provides local after-sales service within one year from the date of sale, but does not include damage caused by improper use. If repair or adjustment is required, please return it, but the shipping cost must be conceited. Damaged on the way, the company will repair the damage of the instrument for free.

Appendix Data Communication

1. Data format

The default data format for Modbus communication is: 9600, n, 8, 1 (baud rate 9600bps, 1 start bit, 8 data bits, no parity, 1 stop bit).

Parameters such as baud rate can be customized.

2. Information frame format (xx means one byte)

a)	Read	data	instr	uction	frame
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Address Function code Register address Number of registers CRC check code (low byte first)

b) Read data response frame

Address Function code Bytes Answer data CRC check code (low byte first)

c) Write data instruction frame

Address Function code Register address Write data CRC check code(low byte first)

d) Write data response frame (same data command frame)

Address Function code Register address Write data CRC check code (low byte first)

3. Register address

Register address	Name	Instruction	Number of registers	Access method
		4 double-byte integers, which		
		are the measured value, the		
40001	Measured value	measured number of decimal	4 (0 hydaa)	Dand
(0x0000)	+ temperature	places, the temperature	4 (8 bytes)	Read
		value, and the decimal value		
		of the temperature value.		
44097		The 0 ~ 20 μs /cm, 0 ~ 200 μs		
(0x1000)	Zero calibration	/cm ranges are calibrated in air,	1 (2 bytes)	Write

the written data is 0; 0 ~ 5000 \[\text{\mu} \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \					
calibrated in air or 0-10% full-scale standard solution, and the written data is the actual value of standard solution ×10. Calibrated in a known standard solution (10% full scale - full scale), the full scale is 0 ~ 20μS / cm write data is the actual value of the standard solution×10: The full scale range is 0 ~ 5000 μ S/cm, the written data is the actual value of standard solution: the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution ×10. 44103 Zero calibration (0x1006) Value The data is read out as a zero offset. The read data is the slope value x 100. Calibrated in solution, the written data is the actual temperature value x 10; the read data is the temperature calibration offset x 10. The default is 6, writing data Write/Rea			the written data is 0; 0 ~ 5000		
full-scale standard solution, and the written data is the actual value of standard solution ×10. Calibrated in a known standard solution (10% full scale - full scale), the full scale is 0 ~ 20μS / cm write data is the actual value of the standard solution×10: The full scale range is 0 ~ 5000 μ S/cm, the written data is the actual value of standard solution: the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution: the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution ×10. 44103 Zero calibration (0x1006) Value The data is read out as a zero offset. The read data is the slope value x 1000. Calibrated in solution, the written data is the actual temperature value x 10; the read data is the temperature calibration offset x 10. The default is 6, writing data Write/Rea			μ s /cm, 0 ~ 200mS/cm range is		
the written data is the actual value of standard solution ×10. Calibrated in a known standard solution (10% full scale is 0 ~ 20µS / cm write data is the actual value of the standard solution×10: The full scale range is 0 ~ 5000 µ S/cm, the written data is the actual value of standard solution: the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution: the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution ×10. 44103 Zero calibration (0x1006) Value The data is read out as a zero offset. 44105 Slope calibration (0x1008) The read data is the slope value × 1000. Calibrated in solution, the written data is the actual temperature value x 10; the read data is the temperature calibration offset x 10. The default is 6, writing data Write/Rea			calibrated in air or 0-10%		
Value of standard solution ×10. Calibrated in a known standard solution (10% full scale - full scale), the full scale is 0 ~ 20μS / cm write data is the actual value of the standard solution×10: The full scale range is 0 ~ 5000 μ S/cm, the written data is the actual value of standard solution: the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution: the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution ×10. The data is read out as a zero offset. 1 (2 bytes) Read 2 bytes Read 1 (2 bytes) Read 1 (3 bytes) Read 1 (4 bytes) Read 1 (5 bytes) Read 1 (6 bytes) Read 1 (7 bytes) Read 1 (8 bytes) Re			full-scale standard solution, and		
Calibrated in a known standard solution (10% full scale - full scale), the full scale is 0 ~ 20μS / cm write data is the actual value of the standard solution×10; The full scale range is 0 ~ 5000 μ S/cm, the written data is the actual value of standard solution; the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution; the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution ×10. The data is read out as a zero offset. The read data is the slope value x 1000. Calibrated in solution, the written data is the actual temperature temperature value x 10; the read data is the temperature calibration offset x 10. The default is 6, writing data Write/Rea			the written data is the actual		
standard solution (10% full scale - full scale), the full scale is 0 ~ 20μS / cm write data is the actual value of the standard solution×10; The full scale range is 0 ~ 5000 μ S/cm, the written data is the actual value of standard solution; the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution; the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution ×10. 44103 Zero calibration (0x1006) Value The data is read out as a zero offset. 44105 Slope calibration (0x1008) Value The read data is the slope value x 1000. Calibrated in solution, the written data is the actual temperature value x 10; the read data is the temperature calibration offset x 10. The default is 6, writing data Write/Rea			value of standard solution \times 10.		
The full scale range is 0 ~ 5000 µ S/cm, the written data is the actual value of standard solution; the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution; the full scale range is 0 ~ 200mS/cm, the written data is the actual value of standard solution ×10. 44103 Zero calibration value Offset. The data is read out as a zero offset. Slope calibration value Value x 1000. Calibrated in solution, the written data is the actual temperature value x 10; the read data is the temperature calibration offset x 10. The default is 6, writing data Write/Rea Write/Rea	44101	Slope	standard solution (10% full scale - full scale), the full scale is 0 $^{\sim}$ 20 μ S / cm write data is the actual value of the		
(0x1006)valueoffset.1 (2 bytes)Read44105 (0x1008)Slope calibration valueThe read data is the slope value x 1000.1 (2 bytes)Read44113 (0x1010)Temperature valueCalibrated in solution, the written data is the actual temperature value x 10; the read data is the temperature1 (2 bytes)Write/Rea48195The default is 6, writing dataWrite/Rea			5000 μ S/cm, the written data is the actual value of standard solution; the full scale range is 0 \sim 200mS/cm, the written data is the actual value of	1 (2 bytes)	Write
(0x1006)valueoffset.44105Slope calibration (0x1008)The read data is the slope value x 1000.1 (2 bytes)Read44113Temperature (0x1010)Calibrated in solution, the written data is the actual temperature value x 10; the read data is the temperature1 (2 bytes)Write/Rea48195The default is 6, writing dataWrite/Rea	44103	Zero calibration	The data is read out as a zero	4 (2 5 1)	5 .
(0x1008) value value x 1000. 1 (2 bytes) Read 44113 (0x1010) Temperature value x 10; the read data is the temperature calibration offset x 10. 1 (2 bytes) Write/Rea 48195 The default is 6, writing data Write/Rea	(0x1006)	value	offset.	1 (2 bytes)	кеаа
(0x1008) value value x 1000. Calibrated in solution, the written data is the actual temperature value x 10; the read data is the temperature calibration offset x 10. The default is 6, writing data Value x 1000. Urite/Rea Write/Rea Write/Rea	44105	Slope calibration	The read data is the slope	1 (2 h. +00)	Dand
44113 Temperature value written data is the actual temperature value x 10; the read data is the temperature calibration offset x 10. 48195 The default is 6, writing data Write/Rea	(0x1008)	value	value x 1000.	1 (2 bytes)	кеаа
48195 The default is 6, writing data Write/Rea		_	written data is the actual temperature value x 10; the read data is the temperature	1(2 bytes)	
(0x2002) Device address range 1-127.		Device address		1 (2 bytes)	-
The calibration value is			The calibration value is		
restored to the default value			restored to the default value		
48225 and the write data is 0. Note:	48225	factory reset	and the write data is 0. Note:	1 (2 hytos)	Write
(0x2020) factory reset The sensor needs to be 1 (2 bytes) Write	(0x2020)		The sensor needs to be	1 (Z Dytes)	
calibrated again after			calibrated again after		
			resetting.		

4. Command example

a) Start measurement instructions

Function: Obtain the conductivity value and temperature of the measuring probe; the unit of

temperature is Celsius, and the value of conductivity is mS/cm (or uS/cm);

Request frame: 06 03 00 00 00 04 45 BE

Response frame: 06 03 08 01 02 00 01 00 B0 00 01 90 48

Example of reading:

Conductivity value	Temperature value
01 02 00 01	00 B0 00 01

For example: Conductivity value 01 02 means hexadecimal reading conductivity value, 00 01 means the conductivity value has no decimal point (the decimal point is related to the range), which is converted to the decimal value of 25.8.

The temperature value 00 B0 represents the hexadecimal reading temperature value, and 00 01 indicates that the temperature value has a decimal point and is converted to a decimal value of 17.6.

b) Calibration instructions

Zero calibration

Function: Set the sensor's conductivity zero calibration value; here the zero calibration is

performed in the air;

Request frame: 06 06 10 00 00 00 8C BD Response frame: 06 06 10 00 00 00 8C BD

Slope calibration

Function: Set the sensor's conductivity slope calibration value; Take a conductivity sensor with a full range of 200.0mS/cm as an example, calibrate in 50mS/cm standard solution,

the written data shall be subject to the actual standard solution value ×10.

Request frame: 06 06 10 04 01 F4 CD 6B Response frame: 06 06 10 04 01 F4 CD 6B

c) Set the device ID address:

Function: set the Modbus device address of the sensor;

Change the device address 06 to 01. The example is as follows:

Request frame: 06 06 20 02 00 01 E3 BD Response frame: 06 06 20 02 00 01 E3 BD

5. Error response

If the sensor does not correctly execute the host command, it will return the following format information:

Definition	Address	Function code	Code	CRC check
Data	ADDR	COM+80H	xx	CRC 16
Number of bytes	1	1	1	2

a) CODE: 01 –Function code error

03 – Data is wrong

b) COM: The received function code